

Arduino Primarily Based Robotic Household Appliance

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ABSTRACT

In a contemporary state of affairs, we have a tendency to all square measure therefore busy with our work that we do not have the time for cleanup our house properly. The answer to the matter is incredibly straightforward, you only ought to purchase a domestic household appliance mechanism such as i-robot roomba which can clean your house with the press of a button. However such industrial merchandise share one common issue, that is price. So today, we can create a simple Floor cleaner mechanism, that isn't solely straightforward to make but prices terribly less compared to commercial merchandise out there within the market. Frequent readers would possibly keep in mind our Arduino Vacuum cleanup mechanism that we have a tendency to Engineer an extended time past, however that one was terribly large and required an enormous accumulator to maneuver around. The new Arduino Vacuum Cleaner should be compact and a lot of sensible. On high of that, this mechanism can have supersonic sensing elements like ultrasonic sensor, IR proximity sensor. The supersonic sensing element can enable the mechanism to avoid obstacles so it will move freely till the space is correctly cleansed, and therefore the proximity sensing element can facilitate it to avoid falling from stairs.

Keywords: Arduino computer code, interfacing of various mechanical and sensing components with Arduino, Obstacle detection, Floor Detection, Management of motor

I. INTRODUCTION

A new report by Oxford economic science claims that robots area unit forecasted to exchange nearly a tenth of the world's producing jobs with the bulk borne by lower-income areas in developed nations. These robots operate semi- or absolutely autonomously to perform services helpful to the well-being of humans and instrumentality. With the aim of keeping our automaton easy as doable, whereas ready to perform the initial goals, i.e. an autonomous vacuum automaton ready to willy-nilly navigate through an area or a house with the minimum human help, cleaner that has intelligent programming and a restricted vacuum cleansing system the subsequent specifications were, Obstacle dodging, Floor detection, Fan motor observance, light-weight Sensing, Real clock System on mechanically.

Many of the fundamental tools used for cleansing throughout history would still be acquainted to us nowadays, from cloths to brooms, brushes and buckets. But more recently, technological solutions to home dirt and dirt—like the vacuum cleaner—have altered our expectations of what 'clean' really

suggests that. a brand new service automaton designed for cleansing tasks in home environments is introduced. System has 3 subsystems: electrical, software system and mechanical of that microcontroller, sensors (opponent and light) and motor area unit the electrical and mechanical systems severally and therefore the software system subsystem is that the brain of the automaton. The cleansing automaton uses a microcontroller to sight obstacles and manipulates its direction as per the inputs. It's programmed to just accept inputs to sense obstacles around it and management the automaton to avoid any collisions. Just in case of AN obstacle, or a possible collision, the microcontroller controls the wheels of the automaton by a motor driver to avoid collision. The vacuum at very cheap of the automaton performs the cleansing method.

II. PROPOSED SYSTEM

We know that within the gift day we have a tendency to area unit tired off with our work that we've less time to take care of the house cleanly.

The solution to the present downside is kind of easy that we'd like to shop for a domestic vacuum automaton that clean the house by pressing the ability button. However the disadvantage of this vacuum is high price. Therefore attributable to this reason we have a tendency to create an easy floor cleaner that is price economical compared to different business merchandise on the market in market.

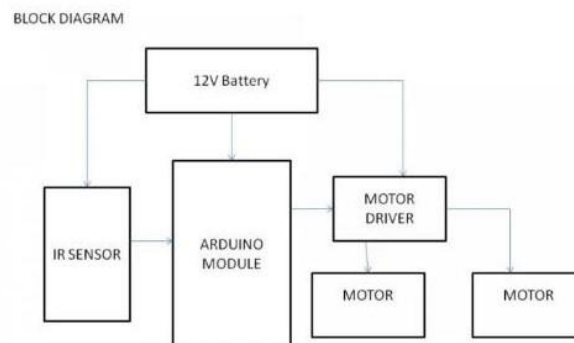


Fig. 1. Block diagram of proposed system.

The Arduino Vacuum cleansing automaton is extremely bulk and required an enormous lead – acid battery to maneuver around. The new Arduino vacuum that was created is compact and additional sensible. It's inaudible sensors to sight the obstacle and IR sensor can facilitate avoiding falling from stairs. We have used the most parts to make a vacuum that's Arduino Uno, Motor driver circuit, battery, inaudible device and IR sensors. The diagram represents the Arduino is interfaced with the motor driver circuit, inaudible sensors and IR sensors and battery to the several pins that's VCC, ground, digital pins and analog pins.

III. ARDUINO UNO

Arduino Uno may be eight bit ATmega328P small controller with non-volatile storage of 32k bytes. It consists of quartz oscillator, serial communication, transformer supports the small controller. It consists of fourteen digital input/output pins of that six are often used as PMW outputs, six analog

input pins, a USB association, power barrel jack and button. The fourteen digital input or output will operate at 5V and supply or receive a most of 40mA current. It works mistreatment the software system Arduino IDE (Integrated development environment). It will be put in on the laptop and might be connected to board with laptop mistreatment USB it's the high performance and low power AVR.

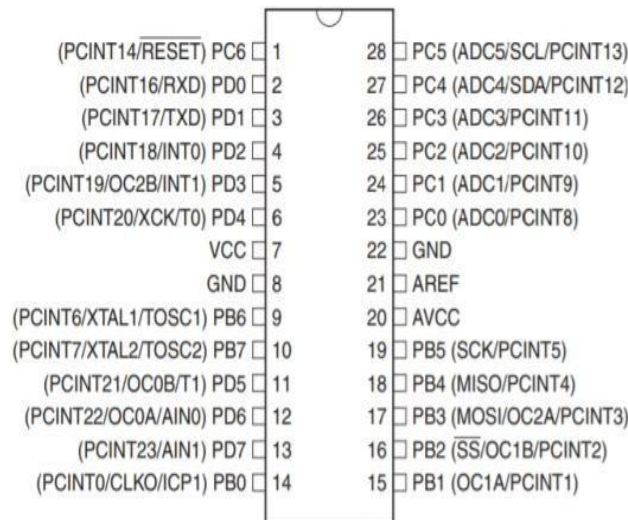


Fig. 2. Pin diagram of Arduino Uno

IV. MECHANISM

Main systems present in this robotic structure are:

- i. Mechanical system
- ii. Processor + Sensor technology + Programming
- iii. Cleaning system

Firstly we connected the trigger and echo pins of 3 ultrasonic sensors to 2, 3, 4, 5, 6, 7, VCC and ground pins of ARDUINO. The IR Sensor is connected to 12Th pin of the ARDUINO. As the motor need four control lines 8, 9, 10, 11 pins in the ARDUINO are the input lines of the motor are interfaced with the input pins in the motor driver IC circuit and output pins in the motor driver circuit is given to the dc motor. And here we are giving supply to controller, motor driver IC circuit and dc motor is 7V which is fed from the battery.

V. PROJECT TOP VIEW

The proposed system has been implemented using crafting materials, sensors, motors and with exhaust fan to collect the dust, dirt.

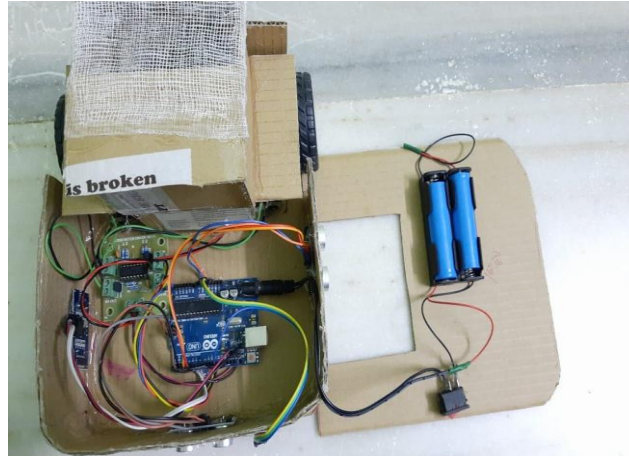


Fig 4: Final Model of proposed system

V. EXPERIMENTAL RESULTS

The proposed system has been implemented in hardware by using cardboard, microprocessor (Arduino), sensors, Rechargeable battery, exhaust fan. Here the dust or dirt will be collected into the box placed at the top of the robot with high automation through the exhaust fan.



Fig 5: Hardware prototype of the proposed system

VI. CONCLUSION

A robotic vacuum is an autonomous robotic vacuum that has intelligent programming and a restricted vacuum cleansing system. Some styles use spinning brushes to succeed in tight corners. Others mix variety of cleansing options (mopping, obstacle detector) coincidental to vacuuming, so rendering the machine into quite simply a automaton "vacuum" cleaner.

Most of the individuals area unit operating and that they didn't have enough time to wash. From time to time technology return up and wish to upgrade for easier human task. Most people sometimes employing a hand controlled vacuum for cleansing. Moreover, most of vacuum robots within the market area unit pricey and will be massive in size. This project is made to be one in all the benefits for human to wash the ground among tiny amount and more practical.

VII. FUTURE DEVELOPMENT

Now we have a tendency to square measure operating to create the mechanism good enough to discover all objects in any position of space. In the future we have a tendency to hope to create the mechanism smarter such once the mechanism cleans any space, save the data regarding obstacle and its location and if the user need to wash an area it simply will restore information and can clean quicker. We hope to create the mechanism to wash tables such it will discover edges and it'll clean the tables while not falling down.

- [1] Robots square measure a very important part in Intelligent Environments.
- [2] Automatic devices.
- [3] Offer physical services.
- [4] Mechanism Systems in these environments would like specific capabilities.
- [5] Autonomous management systems.
- [6] straightforward and natural human-robot interface
- [7] Adaptational and learning capabilities.
- [8] Robots need to maintain safety throughout operation.
- [9] Whereas variety of techniques to handle these necessities exist, no purposeful, satisfactory solutions have however been developed.
- [10] Solely terribly straightforward robots for single tasks in intelligent environments exist.

REFERENCES

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